

# Pump

## Scope of presentation

### Pump

#### Loading valves

#### Filters

#### Control valves

#### Graphic symbols

#### Poppet valves

#### Spool valves

#### Pilot-operated valves

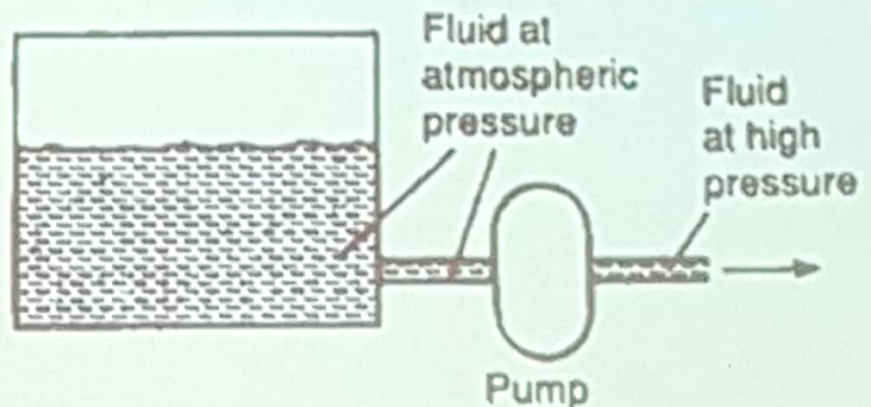
#### Check valves

#### Experiment – 3: Hydraulic Rotary Motor

#### Thanks & Questions

## ➤ Pump

- A hydraulic takes oil from a tank and delivers it to the rest of the hydraulic circuit. In doing so it raises oil pressure to the required level.



(a) Operation of a pump

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## ➤ Pump

- On hydraulic circuit diagrams a pump is represented by the symbol ,with the arrowhead showing the direction of flow.



(b) Pump symbol, arrow shows direction of flow

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## ➤ Pump

- Hydraulic pumps are generally driven at constant speed by a three phase AC induction motor rotating at 1500 *rpm* in the UK (with a 50 Hz supply) and at 1200 or 1800 *rpm* in the USA (with a 60 Hz supply).



# Pump

## ➤ Pump

- Hydraulic pumps are generally driven at constant speed by a three phase AC induction motor rotating at 1500 *rpm* in the UK (with a 50 Hz supply) and at 1200 or 1800 *rpm* in the USA (with a 60 Hz supply).
- There are two types of pump (for fluids) or compressor (for gases).
  1. Hydrodynamic pumps (Non-positive displacement pump), and are primarily used to shift fluid from one location to another at relatively low pressures. Water pumps are a typical application.
  2. a positive displacement or hydrostatic pump. Hydraulic pumps are invariably hydrostatic.

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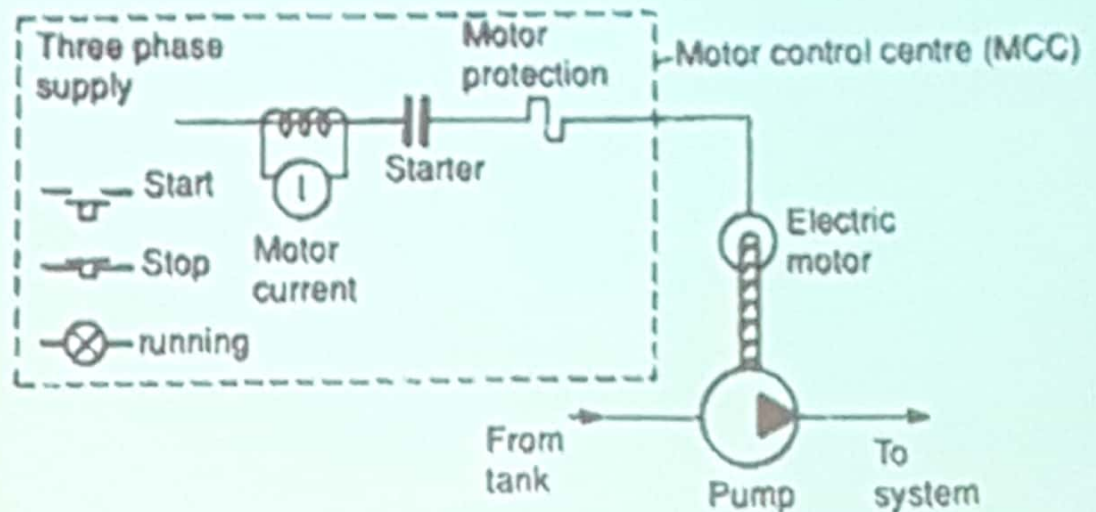
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## Pump



(c) Pump associated components



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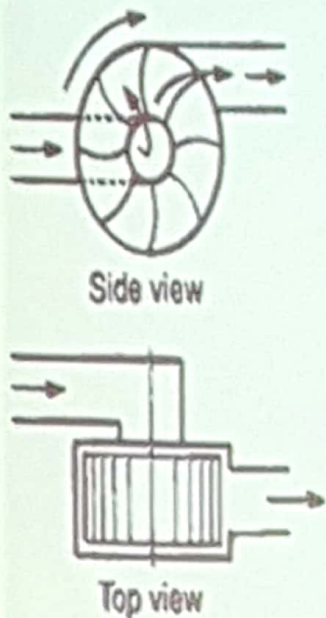
### Thanks & Questions

## ➤ Hydrodynamic pumps (Non-positive displacement pump)

- In these pumps the fluid is pressurized by the rotation of the propeller and the fluid pressure is proportional to the rotor speed
- These pumps can not withstanding high pressures and generally used for low-pressure and high-volume flow applications.
- The fluid pressure and flow generated due to inertia effect of the fluid.
- The fluid motion is generated due to rotating propeller.
- These pumps provide a smooth and continuous flow but the flow output decreases with increase in system resistance (load).

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(a) Hydrodynamic pump

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## ➤ Hydrodynamic pumps (Non-positive displacement pump)

- The flow output decreases because some of the fluid slip back at higher resistance.
- The fluid flow is completely stopped at very large system resistance and thus the volumetric efficiency will become zero. Therefore, the flow rate not only depends on the rotational speed but also on the resistance provided by the system.
- The important advantages of non-positive displacement pumps are lower initial cost, less operating maintenance because of less moving parts.
- These pumps are primarily used for transporting fluids and find little use in the hydraulic or fluid power industries



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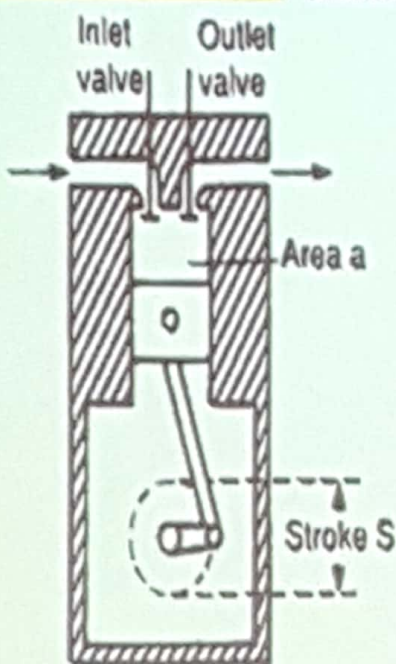
### Experiment – 3: Hydraulic Rotary Motor

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## ➤ positive displacement or hydrostatic pump

- As the piston is driven down, the inlet valve opens and a volume of fluid (determined by the cross section area of the piston and the length of stroke) is drawn into the cylinder.
- Next, the piston is driven up with the inlet valve closed and the outlet valve open, driving the same volume of fluid to the pump outlet.
- Should the pump stop, one of the two valves will always be closed, so there is no route for fluid to leak back.

# Pump



## Positive displacement or hydrostatic pump

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(b) Positive displacement pump

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## ➤ positive displacement or hydrostatic pump

- The important advantages of positive displacement pumps over non-positive displacement pumps include capability to generate high pressures, high volumetric efficiency, high power to weight ratio, change in efficiency throughout the pressure range is small and wider operating range pressure and speed
- The fluid flow rate of these pumps ranges from 0.1 and 1500 gpm, the pressure head ranges between 10 and 10,000 psi
- It is important to note that the positive displacement pumps do not produce pressure but they only produce fluid flow



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### ➤ positive displacement or hydrostatic pump

- More important, though, is the fact that the pump delivers a fixed volume of fluid from inlet to outlet each cycle regardless of pressure at the outlet port. Unlike the hydrodynamic pump.
- Typical efficiencies for pumps range from around 90% (for cheap gear pumps) to about 98% for high quality piston pumps. An allowance for pump efficiency needs to be made when specifying pump capacity or choosing a suitable drive motor.
- The motor power required to drive a pump is determined by the pump capacity and working pressure.

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## ➤ positive displacement or hydrostatic pump

$$\begin{aligned} \text{Power} &= \frac{\text{work}}{\text{time}} \\ &= \frac{\text{force} \times \text{distance}}{\text{time}} \end{aligned}$$

- a pump forces fluid along a pipe of area  $A$  against a pressure  $P$ , moving fluid a distance  $d$  in time  $T$ . The force is  $PA$ , which, when substituted into expression



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$$\text{Power} = \frac{P \times A \times d}{T}$$

but  $A \times d/T$  is flow rate, hence:

$$\text{Power} = \text{pressure} \times \text{flow rate.}$$



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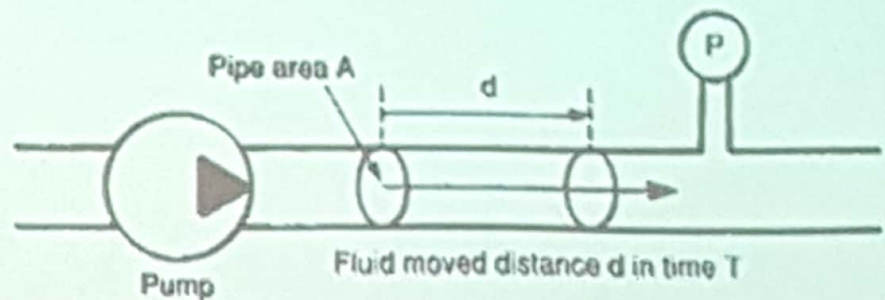
### Experiment – 3: Hydraulic Rotary Motor

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## ➤ positive displacement or hydrostatic pump

- Unfortunately, expression is specified in impractical SI units (pressure in pascal, time in seconds, flow in cubic meters). We may adapt the expression to use more practical units (pressure in bar, flow rate in liter  $s^{-1}$ ) with the expression:

$$Power = \frac{pressure \times flow\ rate}{600} \text{ Kw.}$$



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➤ **positive displacement or hydrostatic pump**

➤ For Imperial systems (pressure in psig, flow rate in *gallons min<sup>-1</sup>*), the expression becomes:

$$\text{Power} = \frac{\text{pressure} \times \text{flow rate}}{1915} \text{ Kw.}$$

$$\text{Horsepower} = 0.75 \times \text{power in Kw.}$$

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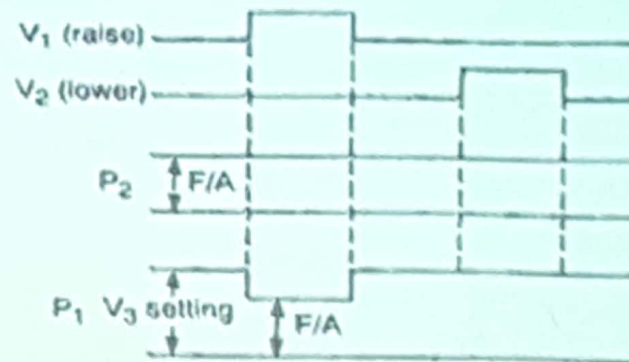
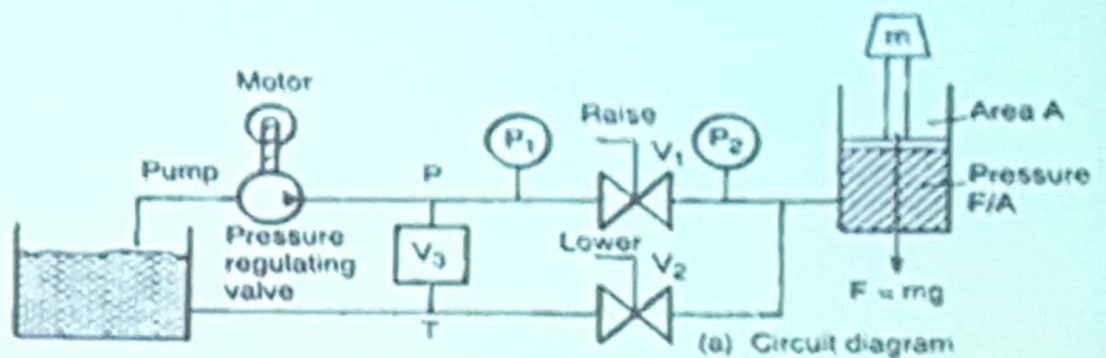
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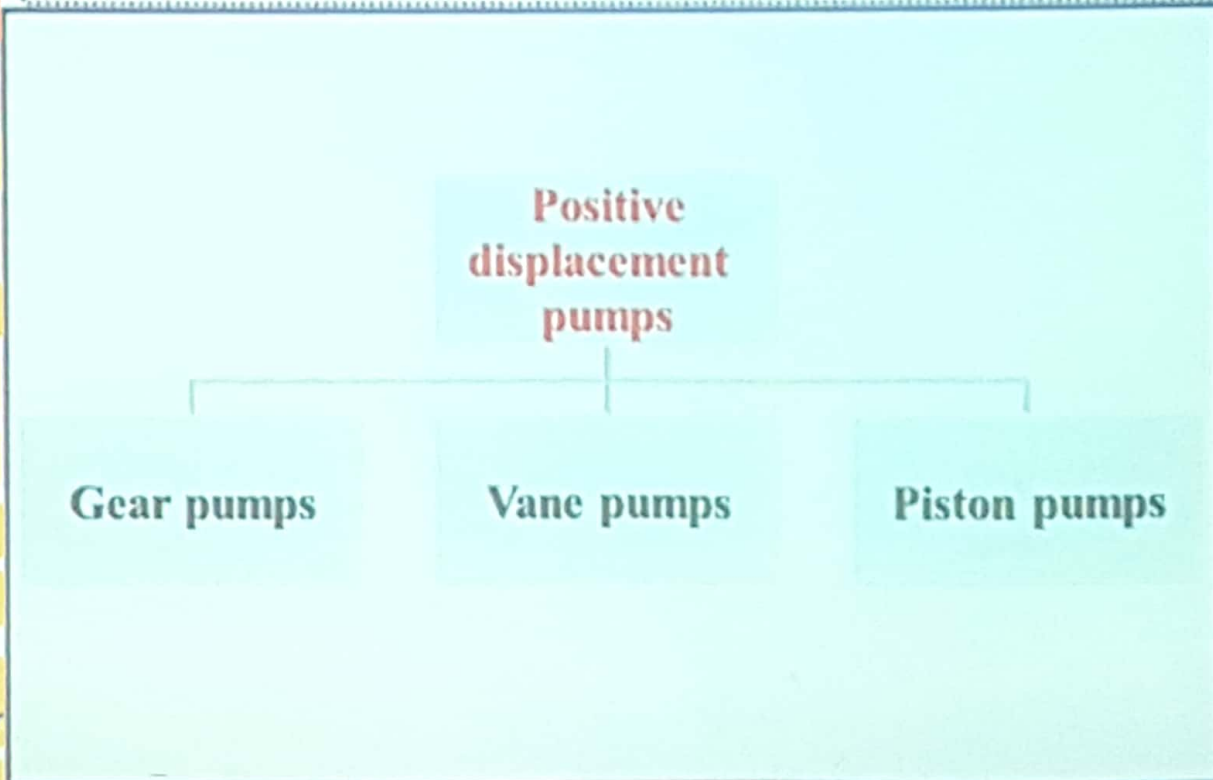




# Pump

**Scope of presentation****Pump****Loading valves****Filters****Control valves****Graphic symbols****Poppet valves****Spool valves****Pilot-operated valves****Check valves****Experiment – 3:  
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## ➤ The Types of Pumps



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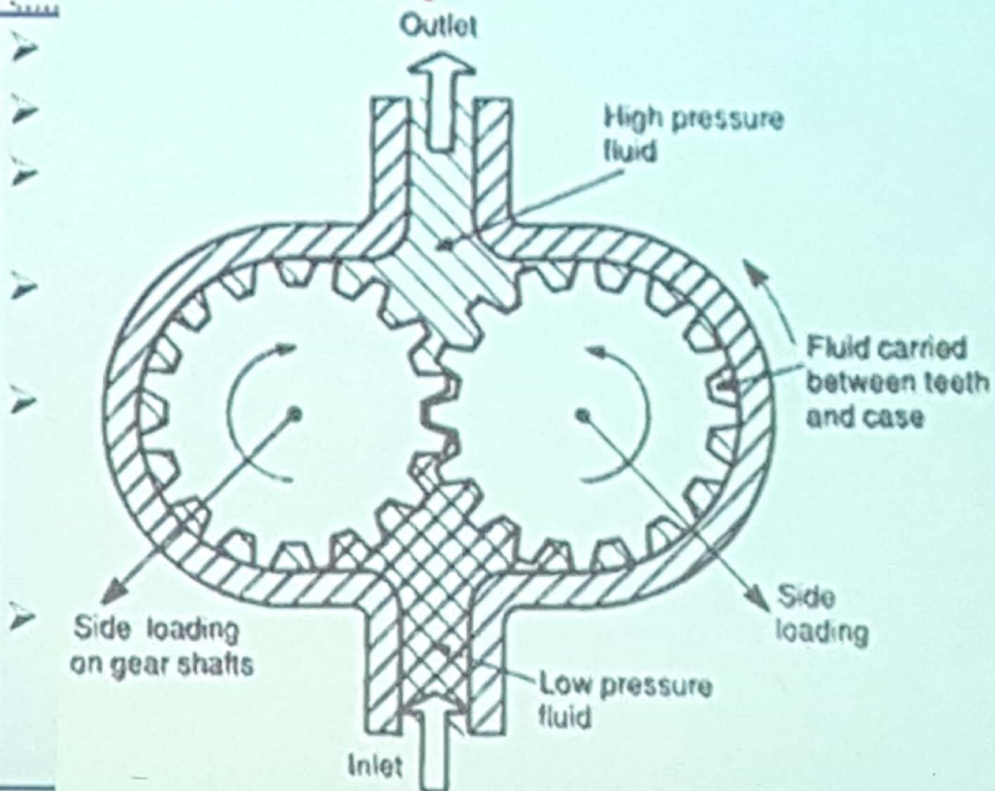
### Pilot-operated valves

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## The Gear Pump



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# Pump

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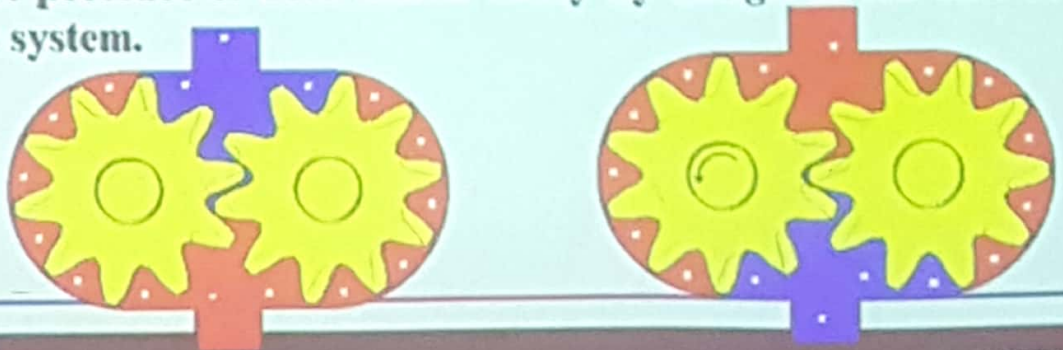
Check valves

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## ➤ The Gear Pump

- Typically, gear pumps are used at pressures up to about 150 bar and capacities of around 150 *gpm* ( $6751 \text{ min}^{-1}$ ). Volumetric efficiency of gear pumps at 90% is lowest of the three pump types.
- Pump displacement is determined by: volume of fluid between each pair of teeth; number of teeth; and speed of rotation. Note the pump merely delivers a fixed volume of fluid from inlet port to outlet port for each rotation; outlet port pressure is determined solely by design of the rest of the system.





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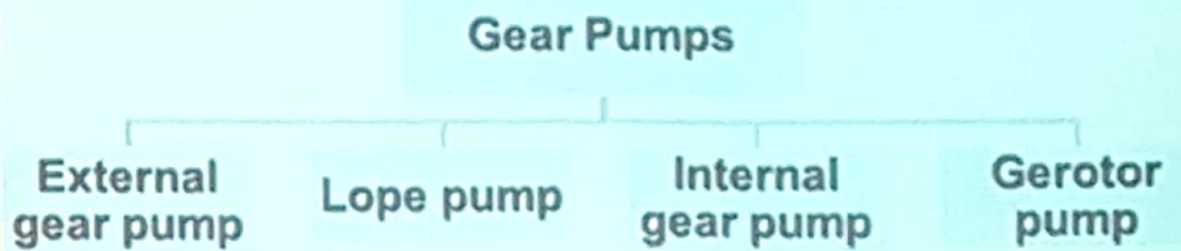
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## ➤ The Gear Pump



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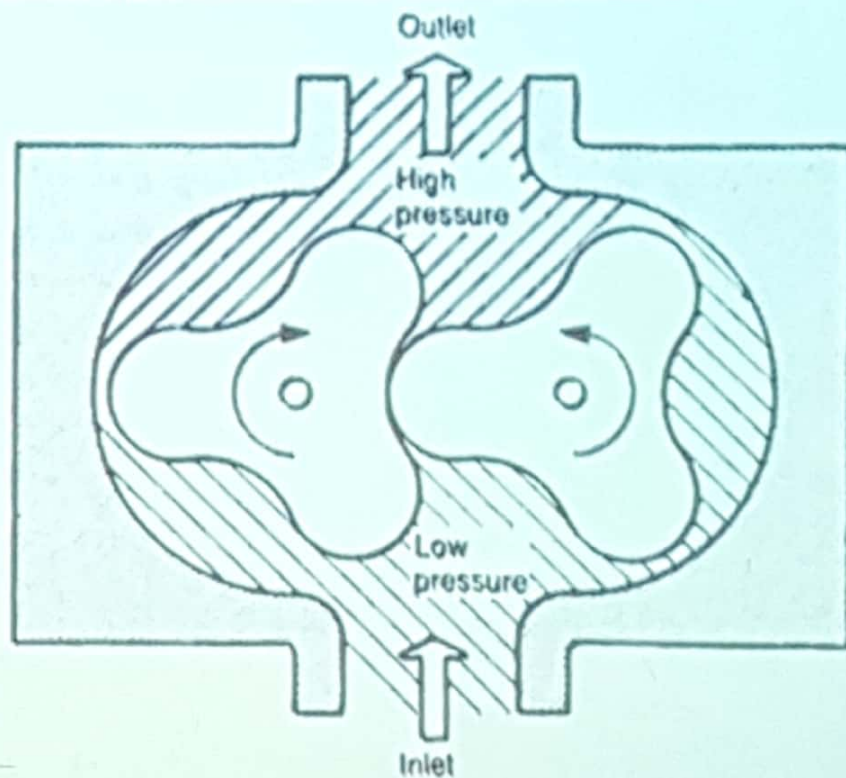
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### ➤ The Lope pump





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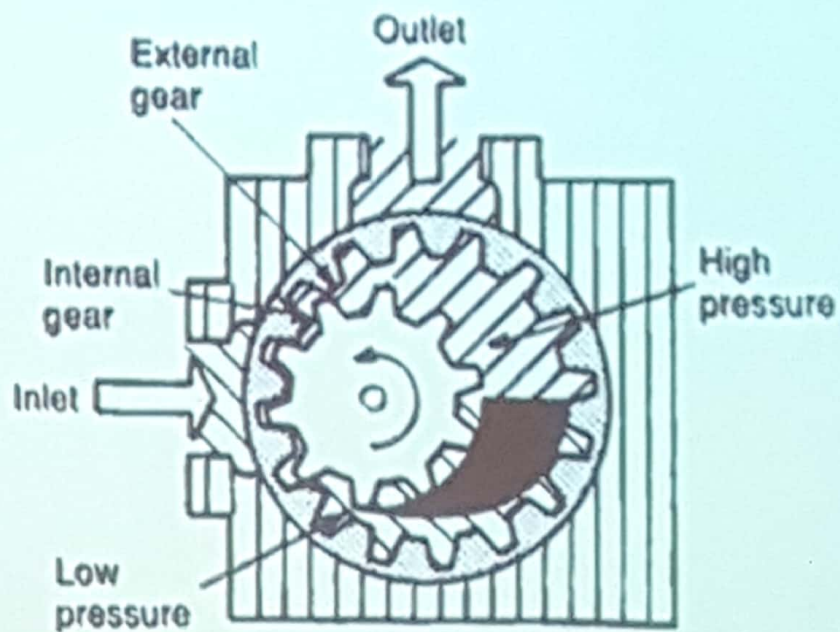
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## ➤ The Internal Gear Pump



(a) Internal gear pump

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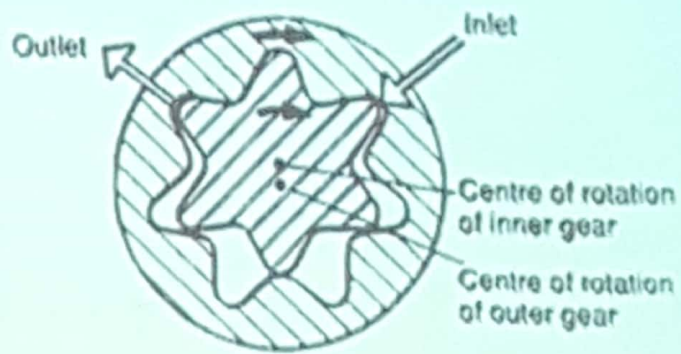
### Pilot-operated valves

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## ➤ The Gerotor Pump



(b) Gerotor pump



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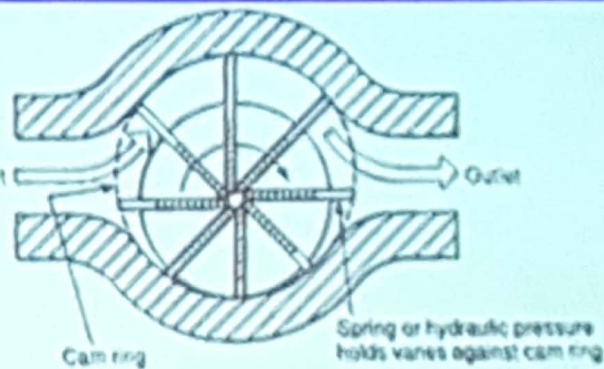
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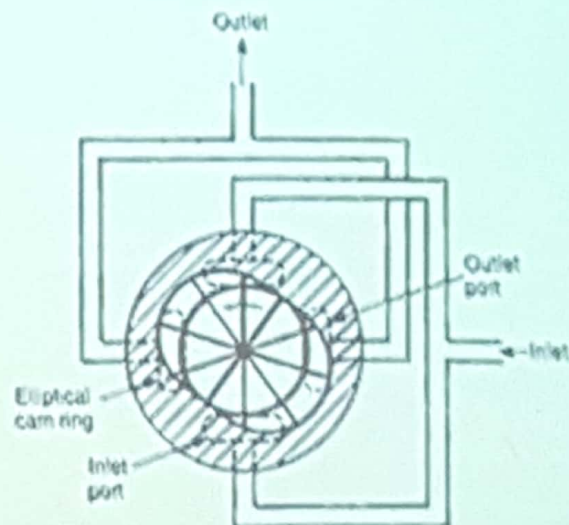
## ➤ The Vane

➤ The major small gap housing.

➤ The vane hydraulic

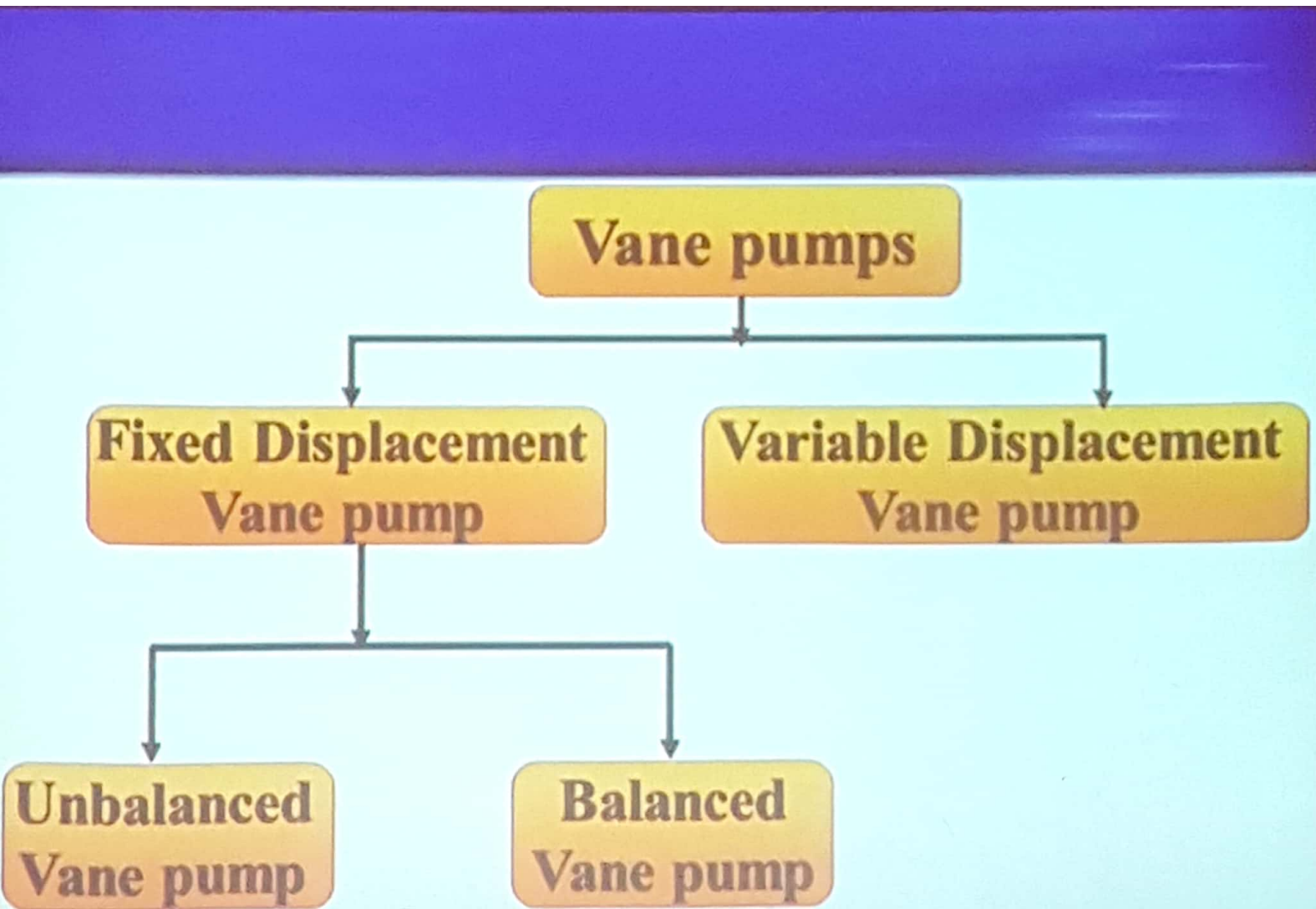


(a) Unbalanced vane pump



(b) Balanced vane pump

arises from the  
teeth and pumpsing spring (or  
rotor.



جهاز العرض يتعرض لإرتفاع كبير في درجة الحرارة.



## **1- Fixed Displacement vane pump**

**In this type of pump the eccentricity between pump cam-ring and rotor is fixed and pump discharge always remain same at a particular pressure.**

**There are two types of fixed displacement Vane Pump:-**

**1- Unbalanced Vane Pump**

**2- Balanced Vane Pump**

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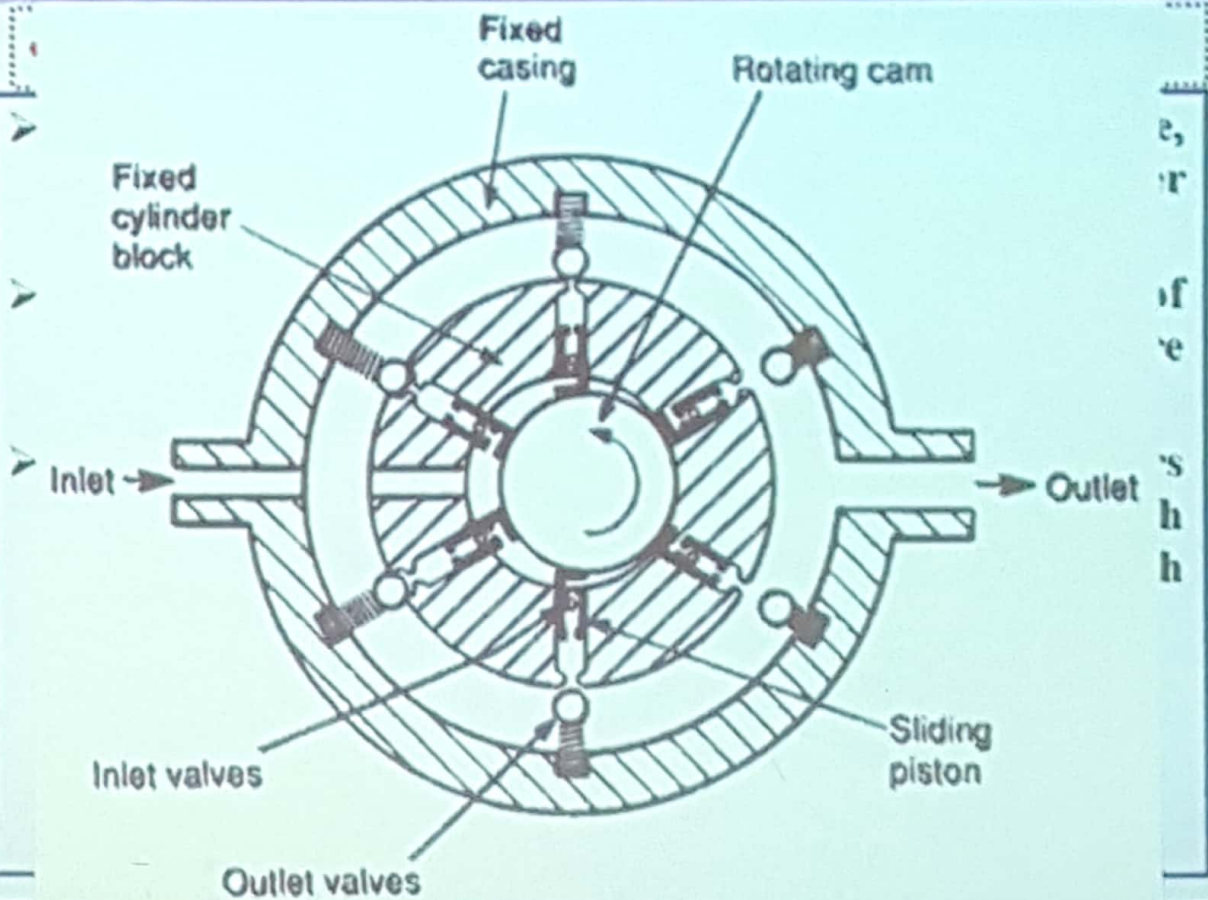
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# Loading and Relief valves

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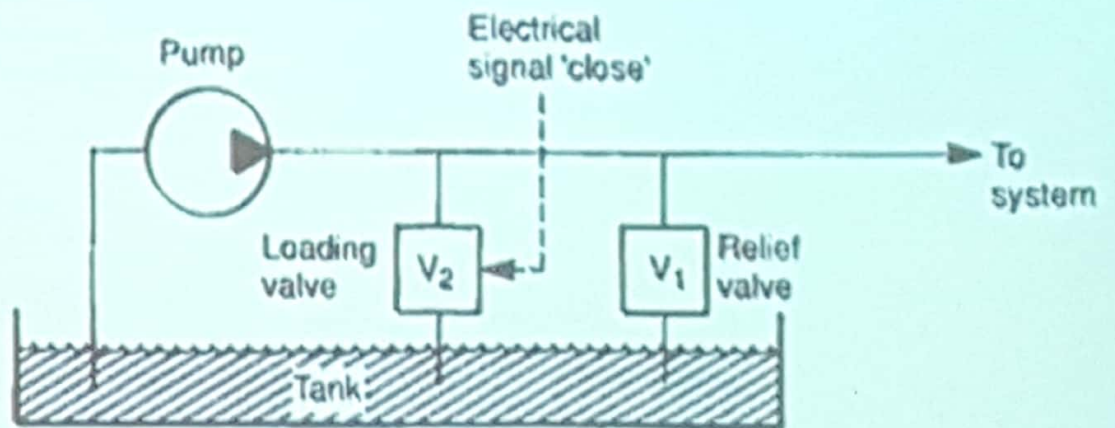
### Pilot-operated valves

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### Experiment – 3: Hydraulic Rotary Motor

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## • The Loading and Relief valves



# Loading and Relief valves

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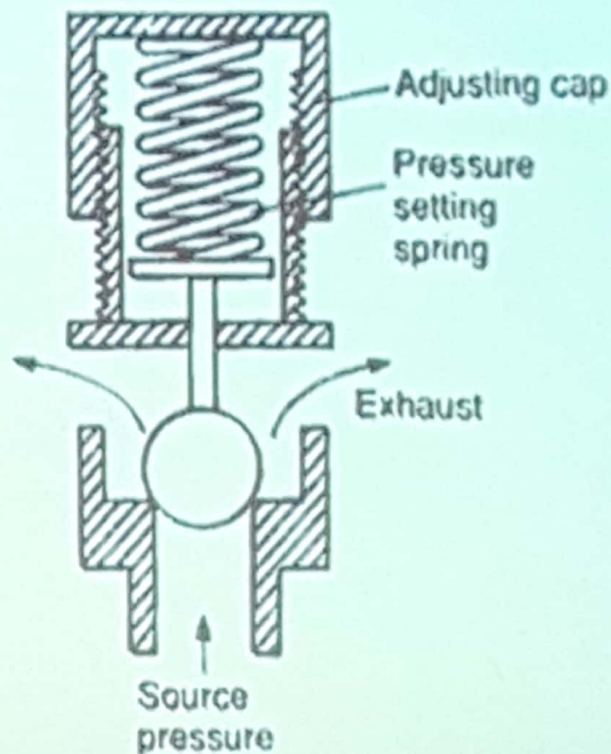
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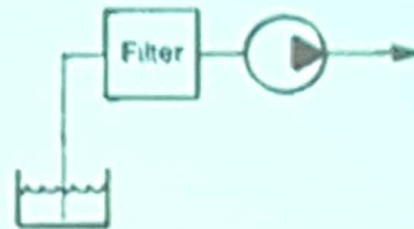
Thanks & Questions

## • The Loading and Relief valves

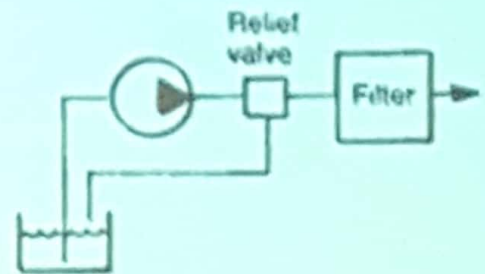


# Filters

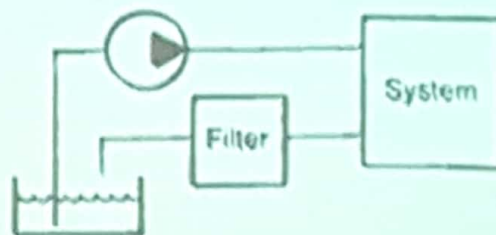
## • The Filters



(a) Inlet line filter



(b) Pressure line filter



(c) Return line filter

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# Filters

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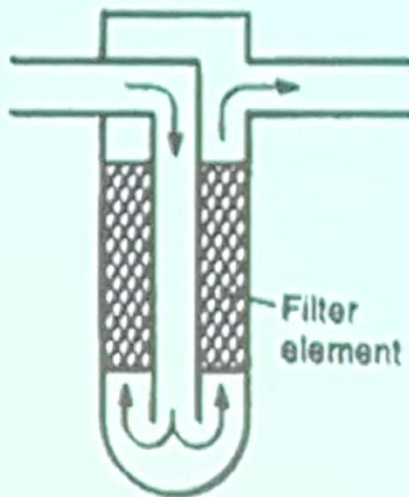
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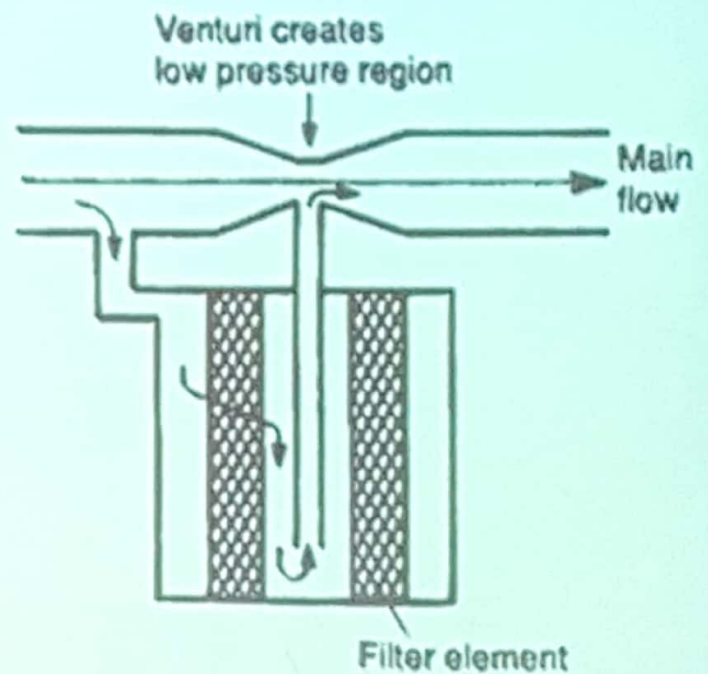
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## • The Filters



(a) Full flow filter



(b) Proportional flow filter

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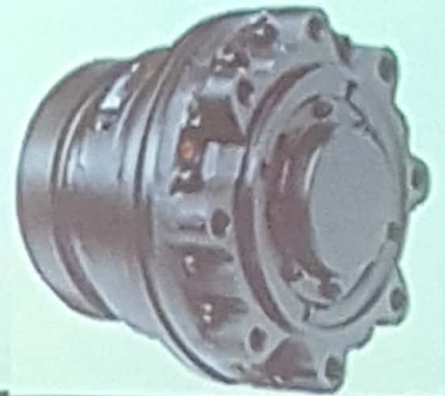
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## • Hydraulic Rotary Motor

Rotary actuators  
(Hydraulic Motors)





# Experiment – 3: Hydraulic Rotary Motor

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Hydraulic Rotary Motor

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## • Hydraulic Rotary Motor

### Purpose

- A hydraulic motor converts hydraulic energy from pressure into rotary motion and torque to drive an implement or system.

### Types

- Fixed positive displacement – gear, piston, gerotor & vane types
- Variable positive displacement – piston

### Typical Applications

- Wheel Motors – drive mobile equipment wheels (skid steers, tractors, lifts)



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## • Hydraulic Rotary Motor

### Typical Applications continued

- Fan Drives – hydraulic fan drives (engine cooling, industrial equipment, drive train cooling, gen sets, grain driers)
- Industrial Machinery – (conveyers, machine tools, cutters, cranes, augers, winches)
- Agricultural Equipment – Harvesters, Trenchers, Lawn Mowers, Forestry Equipment

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## • Hydraulic Rotary Motor

### Fixed Positive Displacement Motors

- Motor displacement is fixed
- Torque is proportional to inlet pressure
- Speed is proportional to flow rate
- Regulate torque and speed with either valves, variable displacement pump or pump speed.

### Gear Motors

- Inlet flow / pressure rotates a gear set causing the output shaft to rotate and create torque



# Experiment – 3: Hydraulic Rotary Motor

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## • Hydraulic Rotary Motor

### Gear Motors

#### Advantages

- Low cost – initial and rebuild
- Good availability / many suppliers
- Cast iron motors have high pressure capability
- Tolerant to contamination
- Compact - desirable packaging

#### Disadvantages

- Lower efficiency compared to other types
- Lower torque per unit displacement compared to piston or Geroter / Geroler types

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# Experiment – 3: Hydraulic Rotary Motor

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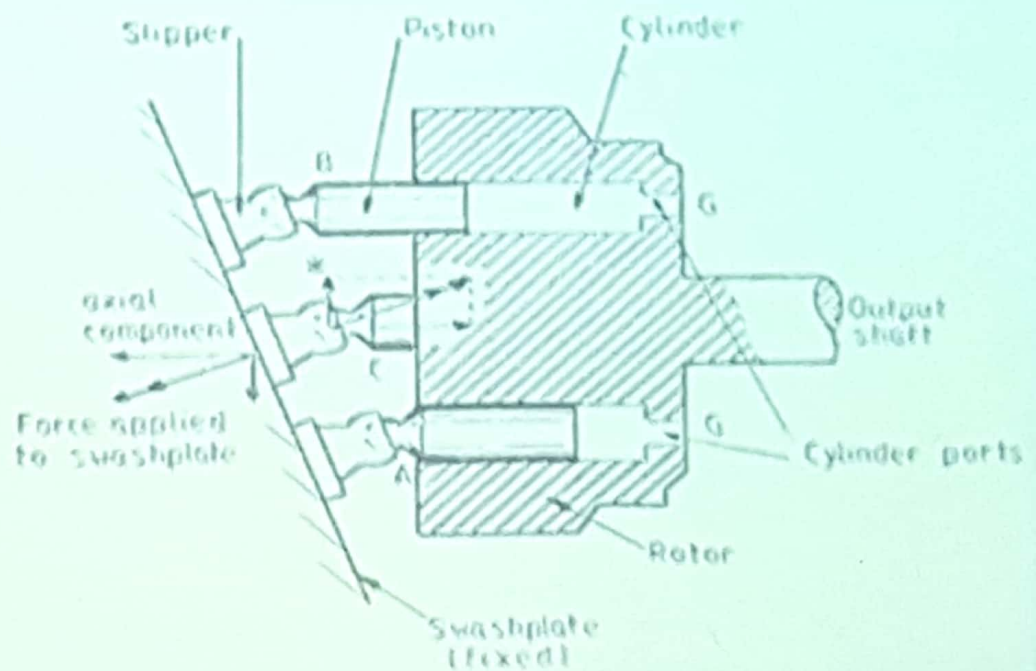
Check valves

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## • Hydraulic Rotary Motor



– Axial-piston Motor

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بدرج تنظيف الفلتر

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## Experiment – 3: Hydraulic Rotary Motor

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### ➤ All hydrostatic motors:

1. Produce a gross torque proportional to flow.
2. Have a velocity proportional to flow.

### ➤ Static friction, running friction and efficiency

- ✓ Static friction or stiction, is the torque that must be applied before the motor will begin to move. It is generally higher than the low-speed running friction.



# Experiment – 3: Hydraulic Rotary Motor

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## ➤ Experiment - Preliminary procedure

1. Connect the outlet of the hydraulic power supply to the 'supply' connection on the servo unit.
2. Connect the return connection to the transparent return hose of the hydraulic reservoir.
3. Plug the rectangular control unit plug into the servo unit socket.
4. Plug the multi-pin plug of the electronic power unit into the control unit socket.
5. Plug the electronic power unit into the electricity supply.
6. Plug the hydraulic power supply unit into the electricity supply. DO NOT start the pump until told.
7. Ensure that the setting of the Orifice Calibrator is fully open.
8. Check the connections between the hydraulic power supply, control unit, servo unit and electronic power supply.